	_					
REG.NO:						
	1 -		. =			
						-



C

DHANALAKSHMI SRINIVASAN COLLEGE OF ARTS & SCIENCE FOR WOMEN (AUTONOMOUS)



(For Candidates admitted from 2019-2020 onwards)

PG DEGREE EXAMINATIONS APRIL – 2021 M.SC - MATHEMATICS CLASSICAL DYNAMICS

Time: 3 Hrs Max.Marks: 75

PART -A

		IANI -A							
HOO	OSE THE CORRECT ANSWER.		(10*1=10						
1.	The number of degrees of freedom is equal	to							
	a) no. of coordinates – no. of equations	b) no. of equations	- no. of coordinates						
	c) no. of equations	d) no. of coordinat	es						
2.	Any system of coordinates which are either fixed or having uniform velocity without rotation is								
	called								
	a) Cartesian system b) Mechanical system	m c)Inertial system	d) Dynamical system						
3.									
	a) zero b) one	c) constant	d) none of these						
4.	A particle of unit mass is attracted by an in	verse square gravitational fo	rce to a fixed point O. This i						
	called	are \$155 co							
	a) Kepler's problem b) Lagrange's proble	em c) Jacobi problem	d) Routhian function						
5.	The Lagrange's equation of motion for imp	oulsive force is							
	a) $\Delta \dot{q}$ =m ⁻¹ \hat{Q} b) $\Delta \dot{q}$ =m ⁻¹ Q_i	c) $\Delta p=m^{-1}\widehat{Q}$	d) $\Delta \dot{q} = \hat{Q}$						
6.	A constraint which is represented by a discontinuous constraint equation is Called								
	a) Constraint impulse	b) Impulsive constraint							
	c) holonomic constraint	d) non-holonomic constrai	nt						
7.	A conservative holonomic system the Hamiltonian function H (q, p) has								
	a) a imaginary value	b) a constant value							
	c) non-constant value	d) none of these							
8.	A conservative holonomic system the Ham	iltonian function H (q, p) is a	equal to the						
	a) Lagrangian b) Total energy		d) Potential energy						

- 9. $\dot{H} = -\frac{\partial L}{\partial t}$ is _____
 - a) Holonomic system

b) non-holonomic system

c) Rhenomicsystem

- d) non-Hamilton function
- 10. Which of the following is Hamilton canonical equation
 - a) $\dot{q}_{j} = \frac{\partial H}{\partial p_{j}}$
- b) $\dot{P}_{j} = -\frac{\partial H}{\partial q_{j}}$
- c) either (a) or (b)
- d) both (a) & (b)

PART-B

ANSWER ALL THE QUESTIONS

(5*7=35)

11. a) State and prove d' Alembert's principle

(OR)

- b) State and Prove work and kinetic energy
- 12. a) Derive the Lagrangian Equation form of d'Alembert's principle.

(OR)

- b) Describe the Routhian function
- 13. a) Explain Gyroscopic forces.

(OR)

- b) Describe Electromagnetic forces
- 14. a) Obtain Hamilton's equation from Lagrange's equations via Legendre transformation.

(OR)

- b) Describe the modified Hamilton's principle.
- 15. a) State and prove Jacobi's theorem

(OR)

b) Derive the canonical integral for Hamilton principal function.

PART-C

ANSWER ANY THREE QUESTIONS

(3*10=30)

- 16. Show that the matrix form of rotational kinetic energy, $T_{rot} = \frac{1}{2}\omega^T I\omega$
- 17. Derive the Lagrange's equation of non-holonomic system.
- 18. Obtain the differential equations of motion using the Routhian procedure and show that the small motion near a reference condition of steady precession.
- 19. Prove that principle of least action.
- 20. Derive the Hamilton-Jacobi equation.